

**Problem 1.** Let  $V$  be an  $n$ -dimensional real vector space equipped with a symmetric, non-degenerate bilinear form  $\langle -, - \rangle: V \times V \rightarrow \mathbf{R}$ .

- (1) Show that  $V$  admits a splitting  $V = P \oplus N$  where  $\langle -, - \rangle$  is positive definite on  $P$  and negative definite on  $N$ . Show that  $p = \dim P$  is unique, that is, depends only on the form  $\langle -, - \rangle$ . The pair of integers  $(\dim P, \dim N)$  is called the *signature* of  $\langle -, - \rangle$ .
- (2) Show that there exists a basis  $\{e_i\}$  for  $V$  such that  $\langle e_i, e_j \rangle = 0$  for  $i \neq j$ ,  $\langle e_i, e_i \rangle = 1$  if  $i = 1, \dots, p$ , and  $\langle e_j, e_j \rangle = -1$  if  $j = p + 1, \dots, n$ .
- (3) Fix a basis as in the previous part of the problem. Let  $T \in \text{End}(V)$  be an endomorphism. Prove that

$$\text{tr}(T) = \sum_{i=1}^n \langle T(e_i), e_i \rangle.$$

**Problem 2.** Let  $G$  be a compact Lie group.

- (1) Show that  $G$  admits a bi-invariant metric  $g$ . That is, a metric which is invariant under both right and left translations. (Hint: Argue that you can always product a left-invariant metric  $g_L$  and a left-invariant volume form  $\omega \in \Omega^{\dim G}(G)$ . Then, show that the metric  $g$  defined by

$$g(v, w) = \frac{1}{\int_G \omega} \int_{x \in G} g_L(dR_x(v), dR_x(w)) \omega$$

is bi-invariant.)

- (2) For  $h \in G$ , consider the inner automorphism  $\text{Ad}_h: G \rightarrow G$  defined by  $\text{Ad}_h(x) = h x h^{-1}$ . Show that  $\text{Ad}_h$  is an isometry with respect to the bi-invariant metric in part (a).
- (3) Let  $\mathfrak{g}$  be the Lie algebra of  $G$  and let  $\text{ad}_h$  be the differential of  $\text{Ad}_h$  at  $e \in G$ . Show that  $\text{ad}_h: \mathfrak{g} \rightarrow \mathfrak{g}$  is a linear isometry (with respect to the metric  $g_e$  on  $\mathfrak{g}$ .)
- (4) Use part (3) to show that

$$g_e([Z, X], Y) = -g_e(X, [Z, Y])$$

for all  $X, Y, Z \in \mathfrak{g}$ .

**Problem 3.** Let  $(M, g)$  be an oriented Riemannian manifold of dimension  $n$ . Define the Riemannian volume form  $\text{dvol}$  as follows:

$$\text{dvol}(v_1, \dots, v_n) = \det(g(v_i, e_j))$$

where  $\{e_i\}$  is a positively oriented orthonormal basis for  $T_p M$ .

- (1) Show that the volume form is parallel.
- (2) Show that in positively oriented coordinates, one has

$$\text{dvol} = \sqrt{\det(g_{ij})} dx^1 \wedge \dots \wedge dx^n.$$

- (3) If  $X$  is a vector field, show that  $L_X \text{dvol} = \text{div}(X) \text{dvol}$ .
- (4) Show that the Laplacian admits the following local formula

$$\Delta u = \frac{1}{\sqrt{\det(g_{ij})}} \partial_k \left( \sqrt{\det(g_{ij})} g^{kl} \partial_l u \right)$$

**Problem 4.** If  $F: M \rightarrow M$  is a diffeomorphism, and  $X$  is a vector field, define the pushforward vector field  $F_* X$  by the formula

$$(F_* X)_p = dF(X_{F^{-1}(p)}).$$

Show that  $F_*(\nabla_X Y) = \nabla_{F_* X} F_* Y$  for any affine connection  $\nabla$ .

**Problem 5.** Let  $G$  be a Lie group. Show that there exists a unique affine connection  $\nabla$  such that  $\nabla X = 0$  for all left-invariant vector fields  $X$ . Show that this connection is torsion-free if and only if  $G$  is abelian.