

September 18 |

Calculus uses the method of linear approximation to study smooth functions (like the line tangent to the graph of a function $\mathbb{R} \rightarrow \mathbb{R}$.)

To make sense of this method for manifolds, we need to define tangent spaces.

In the case of graphs of smooth f 's $\mathbb{R} \rightarrow \mathbb{R}$, this is the 1-dimensional vector space which is tangent to the graph at a pt.

We begin w/ open subsets

$$U \subset \mathbb{R}^n.$$

Given $a \in U$, the tangent space at a is the set

$$T_a U \stackrel{\text{def}}{=} \{a\} \times \mathbb{R}^n = \left\{ \underset{\parallel}{(a, v)} \mid v \in \mathbb{R}^n \right\}.$$

v_a

This set is a vector space w/ operations

$$v_a + w_a = (v + w)_a, \quad \lambda v_a = (\lambda v)_a.$$

Of course, as vector spaces

$$T_a U \cong \mathbb{R}^n,$$

for any $a \in U$.

We could attempt a similar defn for closed subsets of \mathbb{R}^n , but we won't take that approach.

Let's return to derivatives. Recall

$$\frac{\partial f}{\partial x_j}(a) = \frac{d}{dt} f(a + te_j)$$

where e_j is the j^{th} unit vector in \mathbb{R}^n .

Sp. $v \in \mathbb{R}^n$ is any vector. Then we define the v -directional derivative at a :

$$D_v f(a) = \frac{d}{dt} f(a + tv).$$

lem: 1) $D_v(f+g) = D_v f + D_v g$

2) $D_v(fg) = (D_v f)g + f D_v(g)$

as functions of a .

3) $D_v f(a) = v^i \frac{\partial f}{\partial x^i}(a)$.

where $v = v^i e_i$.

This leads to.

Dfn: Let $a \in U \stackrel{\text{open}}{\subset} \mathbb{R}^n$. A

derivation at $a \in U$ is a map

$$\delta : C^\infty(\mathbb{R}^n) \rightarrow \mathbb{R}$$

s.t.

$$1) \delta(f + \lambda g) = \delta f + \lambda \delta g$$

where $\lambda \in \mathbb{R}$.

$$2) \delta(fg) = f(a) \delta g + g(a) \delta f.$$

Let $\text{Der}_a(U)$ be the set of derivations at a . This is naturally a vector space:

$$(\delta_1 + \delta_2) f \stackrel{\text{dfn}}{=} \delta_1 f + \delta_2 f$$

$$(\lambda \delta) f \stackrel{\text{dfn}}{=} \lambda \delta f.$$

Lem: Let $a \in U$, $\delta \in \text{Der}_a(U)$
and $f, g \in C^\infty(\mathbb{R}^n)$.

1) If f is constant then $\delta f = 0$.

2) If $f(a) = g(a) = 0$ then $\delta(fg) = 0$.

Prop: The map

$$T_a U \xrightarrow{\cong} \text{Der}_a(U)$$

$$v_a \longmapsto \left(f \mapsto D_{v_a} f(a) \right)$$

is a linear isomorphism.

Pf: The map is certainly linear. We

show it is injective. Sps $v_a \in T_a U$

is such that

$$\delta_{\nu_a}: f \mapsto D_{\nu} f(a)$$

is the zero derivation. That is

$$\delta_{\nu_a} f = 0 \quad \forall f \in C^{\infty}(\mathbb{R}^n).$$

In a basis write $\nu = \nu^i e_i$, and consider the coordinate functions:

$$x^i: \mathbb{R}^n \rightarrow \mathbb{R}.$$

Then by assumption

$$0 = \delta_{\nu_a}(x^j) = \nu^i \frac{\partial}{\partial x^i}(x^j) = \nu^j.$$

$$\Rightarrow \nu^j = 0 \quad \forall j \quad \Rightarrow \quad \nu = 0$$

Next surjectivity. This follows from the following lemma.

Lemma: Let $\frac{\partial}{\partial x^i}$ be the derivation

$$\frac{\partial}{\partial x^i} f = \frac{\partial f}{\partial x^i}(a)$$

Then $\text{Der}_a(U) = \text{span} \left\{ \frac{\partial}{\partial x^i} \right\}_{i=1}^n$.

Pf: By Taylor's theorem

$$f(x) = f(a) + \sum_{i=1}^n \frac{\partial f}{\partial x^i}(a) (x^i - a^i) + \sum_{i,j=1}^n (x^i - a^i)(x^j - a^j) h_{ij}(x)$$

where $h_{ij}(x)$ is some smooth fn.

For any derivation δ we have

$$\delta \left((x^i - a^i)(x^j - a^j) h_{ij}(x) \right) = 0$$

by previous lemma. Thus

$$\delta f = \sum_{i=1}^n \frac{\partial f}{\partial x^i}(a) (\delta(x^i) - \delta(a^i))$$

$$= \sum_{i=1}^n \frac{\partial f}{\partial x^i}(a) \delta x^i$$

\Rightarrow any δ is a linear combination

of $\left\{ \frac{\partial}{\partial x^i} \right\}$.



From now on we will freely go between

$T_a U$ and $\text{Der}_a(U)$, and will primarily

use the first notation.

Now let M be a smooth mfd.

A linear map

$$\delta : C^\infty(M) \longrightarrow \mathbb{R}$$

is a derivation at $p \in M$ if

$$\delta(fg) = f(p)\delta g + g(p)\delta f.$$

Denote the vector space of all derivations at p by

$$T_p M = \left\{ \begin{array}{l} \text{derivations} \\ \text{at } p \in M \end{array} \right\},$$

which we call the tangent space of M at p .

Lemma: For $\delta \in T_p M$:

$$1) \delta(\text{constant}) = 0, \quad 2) \Rightarrow \begin{array}{l} f(p) = g(p) = 0 \\ \delta(fg) = 0. \end{array}$$